



# Automated Detection of New or Evolving Melanocytic Lesions Using a 3D Body Model

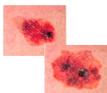
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## Monitoring melanocytic lesions

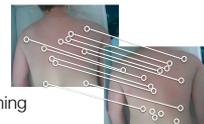
- Malignant melanoma is an aggressive form of skin cancer; its incidence is rapidly increasing worldwide [2]



- Detecting *changes* in an existing lesion or the *appearance* of a new one is crucial for early diagnosis

## Automated systems

- Manual comparison between images taken at different times is challenging and time-consuming



- Approaches in 2D cannot handle non-rigid changes in body shape and pose

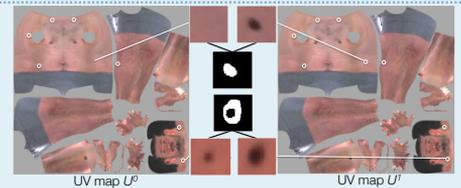
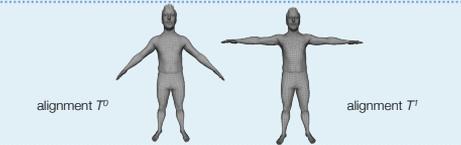
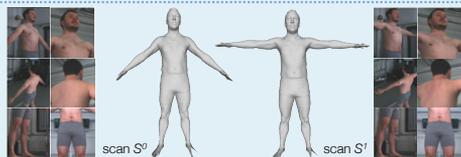
## Scan acquisition



- Scans acquired with a high-accuracy 3D stereo system:
  - 22 pairs of stereo cameras
  - 22 RGB cameras for texture capture

- Fast acquisition: a few milliseconds per scan

## System overview



## Albedo extraction

- Light and albedo estimation, assuming Lambertian skin reflectance and Spherical Harmonics lighting



## Preliminary lesion segmentation



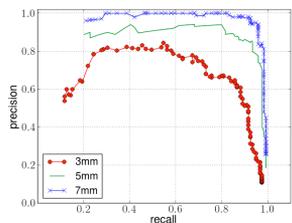
- Laplacian-of-Gaussian (LoG) filtering at 5 scales
- Classification through Linear Discriminant Analysis (LDA)
- Removal of occlusion boundaries / elongated artifacts

## Experimental evaluation

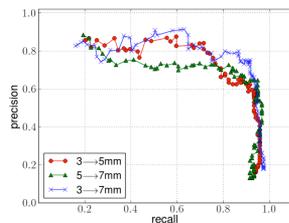
- 12 subjects (6 male, 6 female)
- Variations in skin phenotype and pose



- Synthetic lesions of different diameter (3mm, 5mm, 7mm) drawn on the skin with a marker

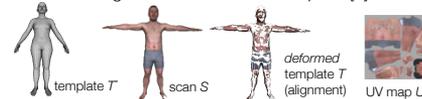


- Precision/recall curves for different values of  $\delta$ , for detecting new lesions (left) and increased lesion sizes (right)



## Model-based registration

- Each scan aligned with a common template [1]



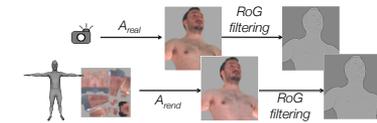
- Objective minimized during registration:

$$E(T, \theta; S) = \lambda_S E_S(T; S) + \lambda_C E_C(T, \theta; S) + \lambda_U E_U(T; S)$$

- $E_S$  penalizes 3D distance between S and T surfaces

- $E_C$  penalizes deviations from the statistical body model, parameterized by pose  $\theta$

- $E_U$  penalizes appearance dissimilarity between S and T



$$E_U(T; S) = \sum_{\text{cameras } j} \sum_{\text{pixels } y} w_{M^j} (RoG_{\sigma_1, \sigma_2}(A_{real}^j)[y] - RoG_{\sigma_1, \sigma_2}(A_{end}^j)[y])^2$$

## Change detection in UV space

- Segmentation refinement based on the 3D model:

weighted majority voting based on all the cameras



mask image

$$\frac{\sum_{\text{cameras } j} M^j \pi^j(x) \max(\omega_{x,j}, 0)}{\sum_{\text{cameras } j} \max(\omega_{x,j}, 0)} > \delta$$

surface normal/viewing vector dot product

- Detection of new lesions or increased lesion size by direct comparison between UV maps

## References

- F. Bogo, J. Romero, M. Loper, M.J. Black, FAUST: Dataset and evaluation for 3D mesh registration. *CVPR* 2014.
- E. Dunki-Jacobs, G. Callender, K. McMasters, Current management of melanoma. *Current Problems in Surgery*, 50: 351–382, 2013.